HCC OAL for RTXC Quadros User Guide

Version 1.20

For use with OAL for RTXC Quadros versions 1.09 and above

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1 System Overview

1.1 Introduction

This guide is for those who want to use HCC Embedded's OS Abstraction Layer (OAL) for their developments in embedded systems which use the RTXC Quadros operating system from Quadros™ Systems, Inc.

The HCC OAL is an abstraction of a Real Time Operating System (RTOS). It defines how HCC software requires an RTOS to behave and its Application Programming Interface (API) defines the functions it requires. Most HCC systems and modules use one or more components of the OAL.

HCC has ported its OAL to RTXC Quadros, in the process creating "hooks" which call RTXC Quadros functions from the HCC abstractions. Once you unzip the files from the **oal_os_quadros** package into the **oal/os** folder in the source tree, these files will automatically call the correct functions.

The OAL API defines functions for handling the following elements:

- Tasks.
- Events – these are used as a signaling mechanism, both between tasks, and from asynchronous sources such as Interrupt Service Routines (ISRs) to tasks.
- Mutexes – these guarantee that, while one task is using a particular resource, no other task can pre-empt it and use the same resource.
- Interrupt Service Routines (ISRs) – in RTXC Quadros ISRs are platform-specific.

1.2 Feature Check

The main features of the module are the following:

- Conforms to the HCC Advanced Embedded Framework.
- Integrated with the HCC OS Abstraction Layer (OAL).
- Fully MISRA-compliant.
- Allows all HCC middleware to run with the RTXC Quadros RTOS.

1.3 Packages and Documents

Packages

The table below lists the packages that you need in order to use the OAL:

Package	Description
oal_base	The OAL base package.
oal_os_quadros	The OAL for RTXC Quadros package. Unzip the files from this package into the **oal/os** folder in the source tree.

Documents

For an overview of HCC RTOS software, see Product Information on the main HCC website.

Readers should note the points in the HCC Documentation Guidelines on the HCC documentation website.

HCC Firmware Quick Start Guide

This document describes how to install packages provided by HCC in the target development environment. Also follow the *Quick Start Guide* when HCC provides package updates.

HCC Source Tree Guide

This document describes the HCC source tree. It gives an overview of the system to make clear the logic behind its organization.

HCC OS Abstraction Layer (Base) User Guide

This document describes the base OAL package, defining the standard functions that must be provided by an RTOS. Use this as your reference to global configuration options and the API.

HCC OAL for RTXC Quadros User Guide

This is this document.

1.4 Change History

This section describes past changes to this manual.

- To view or download earlier manuals, see Archive: OAL for RTXC Quadros User Guide.
- For the history of changes made to the package code itself, see History: oal_os_quadros.

The current version of this manual is 1.20. The full list of versions is as follows:

Manual version	Date	Software version	Reason for change
1.20	2017-06-28	1.09	New *Change History* format.
1.10	2015-04-02	1.05	Added *PSP Porting* section.
1.00	2014-12-04	1.05	First online version.

2 Source File List

This section describes all the source code files included in the system. These files follow the HCC Embedded standard source tree system, described in the *HCC Source Tree Guide*. All references to file pathnames refer to locations within this standard source tree, not within the package you initially receive.

> **Note:** Do not modify any files except the configuration file and PSP files.

2.1 Configuration File

The file **src/config/config_oal_os.h** contains some configurable parameters specific to the system. Configure these as required. For detailed explanations of these, see Configuration Options. (Global configuration parameters are controlled by the base package's configuration file.)

2.2 Source Files

These files are in the directory **src/oal/os**. **These files should only be modified by HCC**.

File	Description
oalp_defs.h	System defines header file.
oalp_event.c	Event functions source code.
oalp_event.h	Event functions header file.
oalp_isr.c	ISR functions source code.
oalp_isr.h	ISR functions header file.
oalp_mutex.c	Mutex functions source code.
oalp_mutex.h	Mutex functions header file.
oalp_task.c	Task functions source code.
oalp_task.h	Task functions header file.

2.3 Version File

The file **src/version/ver_oal_os.h** contains the version number of this module. This version number is checked by all modules that use this module to ensure system consistency over upgrades.

2.4 Platform Support Package (PSP) Files

These files in the directory **src/psp/target/isr** provide functions and elements the core code needs to use, depending on the hardware. Modify these files as required for your hardware.

> **Note:** These are PSP implementations for the specific microcontroller and board; you may need to modify these to work with a different microcontroller and/or development board. See PSP Porting for details.

File	Description
psp_isr.c	ISR functions source code.
psp_isr.h	ISR functions header file.

3 Configuration Options

Note: Systemwide configuration options which allow you to disable certain functions or sets of functions are set in the base package's configuration file. See the *HCC OS Abstraction Layer (Base) User Guide* for details.

Set the RTXC Quadros configuration options in the file **src/config/config_oal_os.h**. This section lists the available configuration options and their default values.

OAL_MUTEX_COUNT

The maximum number of mutexes. The default is 16.

OAL_EVENT_COUNT

The maximum number of events. The default is 16.

OAL_HIGHEST_PRIORITY, OAL_HIGH_PRIORITY, OAL_NORMAL_PRIORITY, OAL_LOW_PRIORITY, OAL_LOWEST_PRIORITY

By default these are respectively 1, 32, 63, 94, and 125.

OAL_EVENT_FLAG

The event flag to use for user tasks invoking internal functions. The default is 0x80.

Note: Do not use a value under 0x80 because lower bits might be used by internal tasks.

OAL_TASK_COUNT

The maximum number of tasks. The default is 4.

OAL_TIMEBASE_COUNTER_ENABLE

Keep this flag at the default of 1 to let the OAL define and initialize the task sleep counter.

Set it to 0 to define your own task sleep counter. In this case the counter name is defined by OAL_TIMEBASE_COUNTER.

OAL_TIMEBASE_COUNTER

The counter name used if you define your own task sleep counter (see the previous option). The default is "mycounter".

4 Implementation Notes

The RTOS elements are implemented as follows.

Events

The configuration option OAL_EVENT_COUNT defines the maximum number of events available for HCC modules.

Mutexes

The configuration option OAL_MUTEX_COUNT defines the maximum number of mutexes available for HCC modules.

Tasks

The configuration option OAL_TASK_COUNT defines the maximum number of tasks available for HCC modules.

Counters

- OAL_TIMEBASE_COUNTER_ENABLE - if this is 1, the task sleep counter is defined and initialized within **oal_task.c**. If you set this option to 0, you can define and initialize the task sleep counter with the name specified by OAL_TIMEBASE_COUNTER.
- OAL_TIMEBASE_COUNTER - the counter name for task sleep.

ISRs

All exceptions used must be configured by using the *RTXCgen* tool as this generates the necessary ISR functions.

The platform ISR is used to enable/disable an ISR or global interrupt.

Ticks

There are no rules governing ticks.

5 PSP Porting

These functions are provided by the PSP to perform various tasks. They are designed for a specific microcontroller and development board. You may need to port them to work with your hardware solution; they are designed to make porting easy.

The package includes samples in the **psp_isr.c** file.

Function	Description
psp_isr_install()	Initializes the ISR.
psp_isr_delete()	Deletes the ISR, releasing the associated resources.
psp_isr_enable()	Enables the ISR.
psp_isr_disable()	Disables the ISR.
psp_int_enable()	Enables global interrupts.
psp_int_disable()	Disables global interrupts.

These functions are described in the following sections.

5.1 psp_isr_install

This function is provided by the PSP to initialize the ISR.

Format

```
int psp_isr_install (
    const oal_isr_dsc_t *   isr_dsc,
    oal_isr_id_t *          isr_id )
```

Arguments

Argument	Description	Type
isr_dsc	The ISR descriptor.	oal_isr_dsc_t *
isr_id	The ISR ID.	oal_isr_id_t *

Return Values

Return value	Description
OAL_SUCCESS	Successful execution.
OAL_ERROR	Operation failed.

5.2 psp_isr_delete

This function is provided by the PSP to delete the ISR, releasing the associated resources.

Format

```
int psp_isr_delete ( oal_isr_id_t isr_id )
```

Arguments

Argument	Description	Type
isr_id	The ISR ID.	oal_isr_id_t

Return Values

Return value	Description
OAL_SUCCESS	Successful execution.
OAL_ERROR	Operation failed.

5.3 psp_isr_enable

This function is provided by the PSP to enable the ISR.

Format

```
int psp_isr_enable ( oal_isr_id_t isr_id )
```

Arguments

Argument	Description	Type
isr_id	The ISR ID.	oal_isr_id_t

Return Values

Return value	Description
OAL_SUCCESS	Successful execution.
OAL_ERROR	Operation failed.

5.4 psp_isr_disable

This function is provided by the PSP to disable the ISR.

Format

```
int psp_isr_disable ( oal_isr_id_t isr_id )
```

Arguments

Argument	Description	Type
isr_id	The ISR ID.	oal_isr_id_t

Return Values

Return value	Description
OAL_SUCCESS	Successful execution.
OAL_ERROR	Operation failed.

5.5 psp_int_enable

This function is provided by the PSP to enable global interrupts.

Format

```
int psp_int_enable ( void )
```

Arguments

None.

Return Values

Return value	Description
OAL_SUCCESS	Successful execution.
OAL_ERROR	Operation failed.

5.6 psp_int_disable

This function is provided by the PSP to disable global interrupts.

Format

```
int psp_int_disable ( void )
```

Arguments

None.

Return Values

Return value	Description
OAL_SUCCESS	Successful execution.
OAL_ERROR	Operation failed.