

HCC OAL for eTaskSync User Guide

Version 1.20

For use with OAL for eTaskSync versions 2.06 and
above

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1 System Overview

1.1 Introduction

This guide is for those who want to use HCC Embedded's OS Abstraction Layer (OAL) for their developments in embedded systems that use HCC's eTaskSync operating system.

The HCC OAL is an abstraction of a Real Time Operating System (RTOS). It defines how HCC software requires an RTOS to behave and its Application Programming Interface (API) defines the functions it requires. Most HCC systems and modules use one or more components of the OAL.

HCC has ported its OAL to its eTaskSync operating system, in the process creating "hooks" which call eTaskSync functions from the HCC abstractions. Once you unzip the files from the **oal_os_sync** package into the **oal/os** folder in the source tree, these files automatically call the correct functions.

The OAL API defines functions for handling the following elements:

- Tasks.
- Events – these are used as a signaling mechanism, both between tasks, and from asynchronous sources such as Interrupt Service Routines (ISRs) to tasks.
- Mutexes – these guarantee that, while one task is using a particular resource, no other task can preempt it and use the same resource.
- Interrupt Service Routines (ISRs) – in eTaskSync ISRs are platform-specific.

1.2 Feature Check

The main features of the module are the following:

- Conforms to the HCC Advanced Embedded Framework.
- Integrated with the HCC OS Abstraction Layer (OAL).
- Fully MISRA-compliant.
- Allows all HCC middleware to run with the eTaskSync RTOS.

1.3 Packages and Documents

Packages

The table below lists the packages that you need in order to use the OAL:

Package	Description
oal_base	The OAL base package.
oal_os_sync	The OAL for eTaskSync package. Unzip the files from this package into the oal/os folder in the source tree.

Documents

For an overview of HCC RTOS software, see [Product Information](#) on the main HCC website.

Readers should note the points in the [HCC Documentation Guidelines](#) on the HCC documentation website.

HCC Firmware Quick Start Guide

This document describes how to install packages provided by HCC in the target development environment. Also follow the *Quick Start Guide* when HCC provides package updates.

HCC Source Tree Guide

This document describes the HCC source tree. It gives an overview of the system to make clear the logic behind its organization.

HCC OS Abstraction Layer (Base) User Guide

This document describes the base OAL package, defining the standard functions that must be provided by an RTOS. Use this as your reference to global configuration options and the API.

HCC OAL for eTaskSync User Guide

This is this document.

1.4 Change History

This section describes past changes to this manual.

- To view or download earlier manuals, see [Archive: OAL for eTaskSync User Guide](#).
- For the history of changes made to the package code itself, see [History: oal_os_sync](#).

The current version of this manual is 1.20. The full list of versions is as follows:

Manual version	Date	Software version	Reason for change
1.20	2017-06-28	2.06	New <i>Change History</i> format.
1.10	2016-02-24	2.05	Added <i>Change History</i> section.
1.00	2014-10-21	2.80	First online version.

2 Source File List

This section describes all the source code files included in the system. These files follow the HCC Embedded standard source tree system, described in the [HCC Source Tree Guide](#). All references to file pathnames refer to locations within this standard source tree, not within the package you initially receive.

Note: Do not modify any files except the configuration file.

2.1 Configuration File

The file `src/config/config_oal_os.h` contains [configuration options](#) specific to the system. Configure these as required. (Global configuration parameters are controlled by the base package's configuration file.)

2.2 Source Files

These files are in the directory `src/oal/os`. **These files should only be modified by HCC.**

File	Description
<code>oalp_defs.h</code>	System defines header file.
<code>oalp_event.c</code>	Event functions source code.
<code>oalp_event.h</code>	Event functions header file.
<code>oalp_isr.c</code>	ISR functions source code.
<code>oalp_isr.h</code>	ISR functions header file.
<code>oalp_mutex.c</code>	Mutex functions source code.
<code>oalp_mutex.h</code>	Mutex functions header file.
<code>oalp_task.c</code>	Task functions source code.
<code>oalp_task.h</code>	Task functions header file.

2.3 Version File

The file `src/version/ver_oal_os.h` contains the version number of this module. This version number is checked by all modules that use this module to ensure system consistency over upgrades.

3 Configuration Options

Note: Systemwide configuration options which allow you to disable certain functions or sets of functions are set in the base package's configuration file. See the [HCC OS Abstraction Layer \(Base\) User Guide](#) for details.

Set the eTaskSync configuration options in the file **src/config/config_oal_os.h**. This section lists the available configuration options and their default values.

OAL_HIGHEST_PRIORITY, OAL_HIGH_PRIORITY, OAL_NORMAL_PRIORITY, OAL_LOW_PRIORITY, OAL_LOWEST_PRIORITY

By default these are respectively 5, 10, 15, 20, and 25.

OAL_EVENT_FLAG

The event flag to use for user tasks invoking internal functions. For example, this is used when a task calls an internal function that needs to wait for an event.

The value of this flag should be over 0x80 because lower bits might be used by internal tasks. The default is 0x100.

OAL_TICK_RATE

The tick rate in ms. The default is 10.

4 Implementation Notes

There are no rules governing events, mutexes, and tasks.

ISRs

The platform ISR is used. The implementation depends on the target microcontroller.

Ticks

The configuration option `OAL_TICK_RATE` sets the tick rate in ms.