

Embedded USB Host Hub Class Driver User Guide

Version 1.40

For use with USBH Hub Class Driver Versions 2.08 and
above

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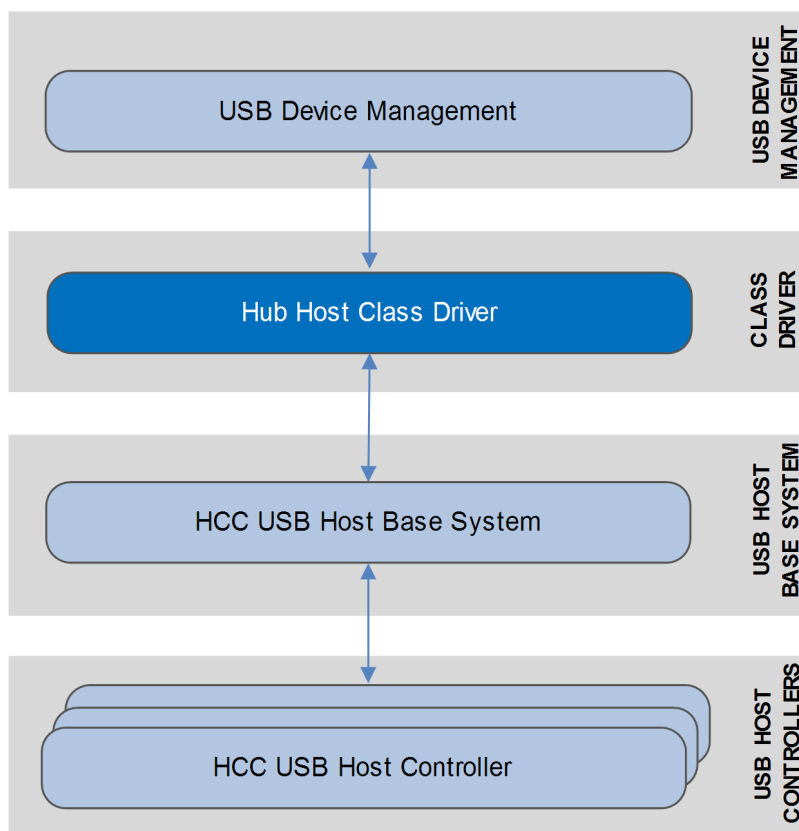
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1 System Overview

1.1 Introduction

This guide is for those who want to implement an Embedded USB hub host class driver to control USB hubs. A USB hub is a device that expands one USB port into multiple ports, providing more ports for connecting devices to a host system. The hub class driver is a passive component of the system; once configured and running, it automatically handles connected hubs without any requirement for application control. The class driver supports multiple nested hubs.

The hub package provides a hub host class driver for a USB stack, as shown below.



Note: Root hubs contained in the host controller are handled automatically by the port manager and are completely independent of this module.

The lower layer interface is designed to use HCC Embedded’s USB Host Interface Layer. This layer is standard over different host controller implementations; this means that the code is unchanged, whichever HCC USB host controller it is interfaced to. For detailed information about this layer, consult the [HCC USB Host Base System User Guide](#) that is shipped with the base system.

The package provides a set of API functions for controlling the device. These are described here.

1.2 Feature Check

The main features of the class driver are the following:

- Conforms to the HCC Advanced Embedded Framework.
- Designed for integration with both RTOS and non-RTOS based systems.
- Compatible with all HCC USB host controllers.
- Supports all devices that conform to the USB Hub specification.
- Supports multiple devices connected simultaneously.
- Supports multiple nested hubs.
- Uses a system of callbacks for user-specified events.

1.3 Packages and Documents

Packages

The table below lists the packages that you need in order to use this module:

Package	Description
<code>hcc_base_doc</code>	This contains the two guides that will help you get started.
<code>usbh_base</code>	The USB host base package. This is the framework used by USB class drivers to communicate over USB using a specific USB host controller package.
<code>usbh_cd_hub</code>	The USB device hub host class driver package described by this document.

Documents

For an overview of HCC's embedded USB stacks, see [Product Information](#) on the main HCC website.

Readers should note the points in the [HCC Documentation Guidelines](#) on the HCC documentation website.

HCC Firmware Quick Start Guide

This document describes how to install packages provided by HCC in the target development environment. Also follow the *Quick Start Guide* when HCC provides package updates.

HCC Source Tree Guide

This document describes the HCC source tree. It gives an overview of the system to make clear the logic behind its organization.

HCC USB Host Base System User Guide

This document defines the USB host base system upon which the complete USB stack is built.

HCC Embedded USB Host Hub Class Driver User Guide

This is this document.

1.4 Change History

This section describes past changes to this manual.

- To view or download earlier manuals, see [Archive: Embedded USB Host Hub Class Driver User Guide](#).
- For the history of changes made to the package code itself, see [History: usbh_cd_hub](#).

The current version of this manual is 1.40. The full list of versions is as follows:

Manual version	Date	Software version	Reason for change
1.40	2017-06-19	2.08	New <i>Change History</i> format.
1.30	2016-04-20	2.08	Added function group descriptions to API.
1.20	2015-03-27	2.08	Added <i>Change History</i>
1.10	2014-08-27	2.07	First release.

2 Source File List

The following sections describe all the source code files included in the system. These files follow the HCC Embedded standard source tree system, described in the [HCC Source Tree Guide](#). All references to file pathnames refer to locations within this standard source tree, not within the package you initially receive.

Note: Do not modify any of these files.

2.1 API Header File

The file `src/api/api_usbh_hub.h` is the only file that should be included by an application using this module. For details of the API functions, see [Application Programming Interface](#).

2.2 Source Code

The file `src/usb-host/class-drivers/hub/usbh_hub.c` is the main code for the module. **This file should only be modified by HCC.**

2.3 Version File

The file `src/version/ver_usbh_hub.h` contains the version number of this module. This version number is checked by all modules that use this module to ensure system consistency over upgrades.

3 Application Programming Interface

This section documents the Application Programming Interface (API). It includes all the functions that are available to an application program.

3.1 Module Management Functions

The functions are the following:

Function	Description
usbh_hub_init()	Initializes the module and allocates the required resources.
usbh_hub_start()	Starts the module.
usbh_hub_stop()	Stops the module.
usbh_hub_delete()	Deletes the module and releases the resources it used.

usbh_hub_init

Use this function to initialize the class driver and allocate the required resources.

Note: You must call this before any other function.

Format

```
int usbh_hub_init ( void )
```

Arguments

Parameter

None.

Return Values

Return value	Description
USBH_SUCCESS	Successful execution.
Else	See Error Codes .

usbh_hub_start

Use this function to start the class driver.

Note: You must call **usbh_hub_init()** before this function.

Format

```
int usbh_hub_start ( void )
```

Arguments

Parameter

None.

Return Values

Return value	Description
USBH_SUCCESS	Successful execution.
Else	See Error Codes .

usbh_hub_stop

Use this function to stop the class driver.

Format

```
int usbh_hub_stop ( void )
```

Arguments

Parameter
None.

Return Values

Return value	
USBH_SUCCESS	Successful execution.
Else	See Error Codes .

usbh_hub_delete

Use this function to delete the class driver and release the associated resources.

Format

```
int usbh_delete ( void )
```

Arguments

Parameter
None.

Return Values

Return value	Description
USBH_SUCCESS	Successful execution.
Else	See Error Codes .

3.2 Hub Management Functions

The functions are the following:

Function	Description
<code>usbh_hub_get_port_hdl()</code>	Gets the hub's port handle.
<code>usbh_hub_present()</code>	Checks whether a hub is connected.
<code>usbh_hub_register_ntf()</code>	Registers a notification function for a specified event type.

usbh_hub_get_port_hdl

Use this function to get the hub's port handle.

Format

```
t_usbh_port_hdl usbh_hub_get_port_hdl ( t_usbh_unit_id uid )
```

Arguments

Parameter	Description	Type
uid	The unit ID.	t_usbh_unit_id

Return Values

Return value	Description
The port handle.	Successful execution.
USBH_PORT_HDL_INVALID	Invalid port handle.
Else	See Error Codes .

usbh_hub_present

Use this function to check whether a hub is connected.

Format

```
int usbh_hub_present ( t_usbh_unit_id uid )
```

Arguments

Parameter	Description	Type
uid	The unit ID.	t_usbh_unit_id

Return Values

Return value	Description
0	No hub is connected.
1	A hub is connected.

usbh_hub_register_ntf

Use this function to register a notification function for a specified event type.

When a device is connected or disconnected, the notification function is called.

Note: It is the user's responsibility to provide any notification functions required by the application. Providing such functions is optional.

Format

```
int usbh_hub_register_ntf (
    t_usbh_unit_id  uid,
    t_usbh_ntf      ntf,
    t_usbh_ntf_fn   ntf_fn )
```

Arguments

Parameter	Description	Type
uid	The unit ID.	t_usbh_unit_id
ntf	The notification ID.	t_usbh_ntf
ntf_fn	The notification function to use when an event occurs.	t_usbh_ntf_fn

Return Values

Return value	Description
USBH_SUCCESS	Successful execution.
Else	See Error Codes .

3.3 Error Codes

If a function executes successfully it returns with a `USBH_SUCCESS` code, a value of 0. The following table shows the meaning of the error codes:

Return Code	Value	Description
<code>USBH_SUCCESS</code>	0	Successful execution.
<code>USBH_SHORT_PACKET</code>	1	IN transfer completed with short packet.
<code>USBH_PENDING</code>	2	Transfer still pending.
<code>USBH_ERR_BUSY</code>	3	Another transfer in progress.
<code>USBH_ERR_DIR</code>	4	Transfer direction error.
<code>USBH_ERR_TIMEOUT</code>	5	Transfer timed out.
<code>USBH_ERR_TRANSFER</code>	6	Transfer failed to complete.
<code>USBH_ERR_TRANSFER_FULL</code>	7	Cannot process more transfers.
<code>USBH_ERR_SUSPENDED</code>	8	Host controller is suspended.
<code>USBH_ERR_HC_HALTED</code>	9	Host controller is halted.
<code>USBH_ERR_REMOVED</code>	10	Transfer finished due to device removal.
<code>USBH_ERR_PERIODIC_LIST</code>	11	Periodic list error.
<code>USBH_ERR_RESET_REQUEST</code>	12	Reset request during enumeration.
<code>USBH_ERR_RESOURCE</code>	13	OS resource error.
<code>USBH_ERR_INVALID</code>	14	Invalid identifier/type (HC, EP HDL, and so on).
<code>USBH_ERR_NOT_AVAILABLE</code>	15	Item not available.
<code>USBH_ERR_INVALID_SIZE</code>	16	Invalid size.
<code>USBH_ERR_NOT_ALLOWED</code>	17	Operation not allowed.
<code>USBH_ERROR</code>	18	General error.

3.4 Types and Definitions

t_usbh_ntf_fn

The `t_usbh_ntf_fn` definition specifies the format of the notification function. It is defined in the USB host base system in the file `api_usb_host.h`.

Format

```
int ( * t_usbh_ntf_fn )(
    t_usbh_unit_id  uid,
    t_usbh_ntf      ntf )
```

Arguments

Parameter	Description	Type
uid	The unit ID.	t_usbh_unit_id
ntf	The notification code .	t_usbh_ntf

Notification Codes

The standard notification codes shown below are defined in the USB host base system in the file `api_usb_host.h`. This module has no specific notification codes of its own.

Notification	Value	Description
USBH_NTF_CONNECT	1	Connection notification code.
USBH_NTF_DISCONNECT	2	Disconnection notification code.

4 Integration

This section specifies the elements of this package that need porting, depending on the target environment.

4.1 PSP Porting

The Platform Support Package (PSP) is designed to hold all platform-specific functionality, either because it relies on specific features of a target system, or because this provides the most efficient or flexible solution for the developer.

The module makes use of the following standard PSP macros:

Macro	Package	Component	Description
PSP_RD_LE16	psp_base	psp_endianness	Reads a 16 bit value stored as little-endian from a memory location.
PSP_WR_LE16	psp_base	psp_endianness	Writes a 16 bit value to be stored as little-endian to a memory location.